Getting Down To Earth

A practical guide to earth resistance testing

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Introduction

Nothing is quite so common or abundantly available throughout the world as the earth’s soil. We are more apt to think of earth as something to be tilled for planting or to be excavated for a building foundation. Yet, it also has an electrical property -- conductivity (or low resistance) -- that is put to practical use every day in industrial plants and utilities.

Broadly speaking, “earth resistance” is the resistance of soil to the passage of electric current. Actually, the earth is a relatively poor conductor of electricity compared to normal conductors like copper wire. But, if the area of a path for current is large enough, resistance can be quite low and the earth can be a good conductor. It is the earth’s abundance and availability that make it an indispensable component of a properly functioning electrical system.

Earth resistance is measured in two ways for two important fields of use:

1. Determining effectiveness of “ground” grids and connections that are used with electrical systems to protect personnel and equipment.
2. Prospecting for good (low resistance) “ground” locations, or obtaining measured resistance values that can give specific information about what lies some distance below the earth’s surface (such as depth to bedrock).

It is not the intent of this manual to go too deeply into the theory and mathematics of the subject. As noted in the references at the end, there are many excellent books and papers that cover these. Rather, the information herein is in simple language for easy understanding by the user in industry.

From years of experience in supplying instruments for the tests involved, Megger can provide advice to help you make specific tests. We would be pleased to have a representative call on you to discuss your problem.
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Safety

There is an inherent safety problem in earth resistance testing that requires care and planning by the user of the test set.

The possibility exists that a fault in the power system will cause a high current to flow into the ground system while the test is in progress. This may cause unexpected high voltages to appear at the current and voltage probes and also at the terminals of the test set.

This risk must be evaluated by the person responsible for the tests, taking into account the fault current available and expected step-and-touch potentials. IEEE Standard 80 entitled “IEEE Guide for Safety in AC Substation Grounding” fully covers this subject. (Other standards may prevail elsewhere in the world.)

We recommend that the operator wear rubber protective gloves (ANSI/ASTM D120 or equal) while handling connections and use a rubber safety mat (ANSI/ASTM D178 or equal) while operating the test set.

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Getting Down to Earth

Factors That Can Change Your Minimum Earth Resistance

We will discuss later what value of earth resistance is considered low enough. You’ll see that there is no general rule usable for all cases. First, however, consider three factors that can change the earth electrode requirements from year to year:

- A plant or other electrical facility can expand in size. Also, new plants continue to be built larger and larger. Such changes create different needs in the earth electrode. What was formerly a suitably low earth resistance can become an obsolete “standard.”
- As facilities add more modern sensitive computer-controlled equipment, the problems of electrical noise is magnified. Noise that would not affect cruder, older equipment can cause daily problems with new equipment.
- As more nonmetallic pipes and conduits are installed underground, such installations become less and less dependable as effective, low-resistance ground connections.
- In many locations, the water table is gradually falling. In a year or so, earth electrode systems that formerly were effective may end up in dry earth of high resistance.

These factors emphasize the importance of a continuous, periodic program of earth-resistance testing. It is not enough to check the earth resistance only at the time of installation.

Some Basic Definitions

First, let’s define our terms. As early as 1918\(^1\), the terms ground, permanent ground, and ground connections were defined to mean “electrical connections intentionally made between electrical bodies (or conducting bodies in close proximity to electrical circuits) and metallic bodies in the earth — such as rods, water pipes, plates, or driven pipes.”

---

\(^1\) Reference 19
The metallic body in the earth is often referred to as an electrode even though it may be a water-pipe system, buried strips or plates, or wires. Such combinations of metallic bodies are called a grid. The earth resistance we’re concerned with is the resistance to current from the electrode into the surrounding earth.

To appreciate why earth resistance must be low, you need only use Ohm’s Law: \( E = I \times R \) where \( E \) is volts; \( R \), the resistance in ohms; and \( I \), the current in amperes. Assume that you have a 4000-V supply (2300 V to ground) with a resistance of 13 \( \Omega \) (see Fig. 2). Now, assume that an exposed wire in this system touches a motor frame that is connected to a grounding system which has a 10-ohm resistance to earth.

By Ohm’s Law, there will be a current of 100 A\(^2\) through the fault (from the motor frame to the earth). If you happen to touch the motor frame and are grounded solidly to earth, (by standing in a puddle) you could be subjected to 1000 V (10 \( \Omega \) x 100 A).

As you’ll note from point 2 in the following, this may be more than enough to kill you instantly. If, however, the earth resistance is less than 1 \( \Omega \), the shock you’d get would be under 100 V (1 x 100) and you’d probably live to correct the fault.

---

**Fig. 2: Example of an electrical circuit with too high an earth resistance**

\[ I = \frac{E}{R} = \frac{2300}{13} = 100 \text{ amperes} \]
Resistance to earth can vary with changes in climate and temperature. Such changes can be considerable. An earth electrode that was good (low-resistance) when installed may not stay that way; to be sure, you must check it periodically.

We cannot tell you what your maximum earth resistance should be. For specific systems in definite locations, specifications are often set. Some call for $5 \Omega$ maximum; others accept no more than $3 \Omega$. In certain cases, resistances as low as a small fraction of an ohm are required.

**Nature of an Earth Electrode**

Resistance to current through an earth electrode actually has three components (Fig. 4):

1. Resistance of the electrode itself and connections to it.
2. Contact resistance between the electrode and the soil adjacent to it.
3. Resistance of the surrounding earth.

National Electrical Code Maximum Values

The National Electrical Code, Section 250-56 states that a single electrode with a resistance to ground greater than $25 \Omega$ shall be augmented by one additional electrode. (Other standards may prevail elsewhere in the world.)

We recommend that single-electrode grounds be tested when installed and periodically afterward.
Electrode Resistance: Rods, pipes, masses of metal, structures, and other devices are commonly used for earth connections. These are usually of sufficient size or cross-section that their resistance is a negligible part of the total resistance.

Electrode-Earth Contact Resistance: This is much less than you might think. If the electrode is free from paint or grease, and the earth is packed firmly, contact resistance is negligible. Rust on an iron electrode has little or no effect; the iron oxide is readily soaked with water and has less resistance than most soils. But if an iron pipe has rusted through, the part below the break is not effective as a part of the earth electrode.

Resistance of Surrounding Earth: An electrode driven into earth of uniform resistivity radiates current in all directions. Think of the electrode as being surrounded by shells of earth, all of equal thickness (see Fig. 4).

The earth shell nearest the electrode naturally has the smallest surface area and so offers the greatest resistance. The next earth shell is somewhat larger in area and offers less resistance. Finally, a distance from the electrode will be reached where inclusion of additional earth shells does not add significantly to the resistance of the earth surrounding the electrode. It is this critical volume of soil that determines the effectiveness of the ground electrode and which therefore must be effectively measured in order to make this determination. Ground testing is distinct when compared to more familiar forms of electrical measurement, in that it is a volumetric measurement and cannot be treated as a “point” property.

Generally, the resistance of the surrounding earth will be the largest of the three components making up the resistance of a ground connection. The several factors that can affect this value are discussed in Section II on Earth Resistivity. From Section II, you’ll see that earth resistivity depends on the soil material, the moisture content, and the temperature. It is far from a constant, predictable value ranging generally from 500 to 50,000 ohm-cm $^3$.

Principles Involved in Earth Resistance Testing

The resistance to earth of any system of electrodes theoretically can be calculated from formulas based upon the general resistance formula:

$$ R = \rho \frac{L}{A} $$

where $\rho$ is the resistivity of the earth in ohm-cm, L is the length of the conducting path, and A is the cross-sectional area of the path. Prof. H. B. Dwight of Massachusetts Institute of Technology developed rather complex formulas for the calculation of the resistance to earth for any distance from various systems of electrodes (Reference 11). All such formulas can be simplified a little by basing them on the assumption that the earth’s resistivity is uniform throughout the entire soil volume under consideration.

---

3 An ohm-centimeter (abbreviated ohm-cm) is defined as the resistance of a cube of material (in this case, earth) with the cube sides being measured in centimeters.
To understand the principle of earth testing, consider the schematic diagram in Fig. 5a. Bear in mind our previous observation with reference to the earth shell diagram in Fig. 4: with increased distance from an electrode, the earth shells are of greater surface area and therefore of lower resistance. Now, assume that you have three rods driven into the earth some distance apart and a voltage applied, as shown in Fig. 5a. The current between rods 1 and 2 is measured by an ammeter; the potential difference (voltage) between rods 1 and 3 is measured by a voltmeter.

If rod 3 is located at various points between rods 1 and 2, preferably in a straight line, you can get a series of voltage readings. By Ohm’s Law \( R = \frac{E}{I} \) you can determine the earth resistance at any point measured. For example, if the measured voltage \( E \) between rods 1 and 3 is 30 V and the measured current \( I \) is 2 A, the resistance of the earth \( R \) at that point would be 15 \( \Omega \).

The series of resistance values can be plotted against distance to obtain a curve (Fig. 5b). Note that as rod 3 is moved away from rod 1, the resistance values increase, but the amount of increase gets less and less until a point is reached where the rate of increase becomes so small that it can almost be considered constant (20 \( \Omega \) in Fig. 5b). The earth shells between the two rods (1 and 3) have so great a surface area that they add little to the total resistance. Beyond this point, as rod 3 approaches the earth shells of rod 2, resistance gradually picks up. Near rod 2, the values rise sharply.

Now, let’s say that rod 1 is our earth electrode under test. From a typical earth-resistance curve, such as Fig. 5b, what is the resistance to earth of this rod? We call rod 2 current-reference probe \( C \) and rod 3, potential-reference probe \( P \) (simply for convenience in identification). The correct resistance is usually obtained if \( P \) (rod 3) is placed at a distance from the center of the earth electrode (rod 1) about 62 percent of the distance between the earth electrode and \( C \) (rod 2).

4 Actually, current can exist in other paths between the two fixed electrodes, so that rod 3 could be (and might have to be) located at other than along a straight line.
For example, in Fig. 5b, the distance D from the earth electrode to C is 100 ft. Taking 62 percent of this distance, we get 62 ft. From Fig. 5b, the resistance for this distance is 20 Ω. This is the measured resistance of the earth electrode.

This rule works well for simple electrodes, such as a driven rod. It also works for a small group of rods. But you must know the true electrical center of the electrode system fairly accurately. Also, accuracy of readings is better if the earth resistivity between the three electrodes is reasonably constant. Finally, C should be far enough away from the earth electrode so that the 62 percent distance is out of the “sphere of influence” of the earth electrode. (See discussion with reference to Figs. 8 and 9). For the test, the electrode should be isolated from the electrical system that it is protecting; otherwise, the whole system is tested which (depending on local practices) may include the pole ground, system neutral, and transformer ground. This obscures the specific effect of the local ground.

Basic Test Methods for Earth Resistance

The earth tester generates an a.c. signal which is fed into the system under test. The instrument then checks the status of the circuits for good connection and noise. If either of these variables is out of specification then the operator is informed. Having checked that the conditions for test are met, the instrument automatically steps through its measurement ranges to find the optimum signal to apply. Measuring the current flowing and the voltage generated the instrument calculates and displays the system resistance in the range of 0.001 to 20,000 ohms, depending on the model chosen.

There are three basic test methods as noted below. The first two are shown schematically in Figs. 6 and 7.

1. Fall-of-potential method, or three-terminal test.
2. Dead Earth method (two-point test).
3. Clamp-on test method (see Appendix II).
The added accuracy may prove significant when meeting very low resistance specifications or using test methods that necessitate an extra digit of measurement in order to meet the mathematical requirements. The decision is optional, based on the operator’s testing goals and the method used. The driven reference rod C should be placed as far from the earth electrode as practical; this distance may be limited by the length of extension wire available, or the geography of the surroundings (see Fig. 6). Leads should be separated and “snaked,” not run close and parallel to each other, to eliminate mutual inductance.

Potential-reference rod P is then driven in at a number of points roughly on a straight line between the earth electrode and C. Resistance readings are logged for each of the points. A curve of resistance vs. distance, like Fig. 5b, is then drawn. Correct earth resistance is read from the curve for the distance that is about 62 percent of the total distance from the earth electrode to C. In other words, if the total distance is D, the 62 percent distance is 0.62D; for example, if D is 120 ft, the distance value for earth resistance is 0.62 x 120 or 74 ft.

There are three basic types of the Fall-of-Potential test methods and a number of related test methods that will be described in the appendices. The types of Fall-of-Potential are:

- **Full Fall-of-Potential** — a number of tests are made at different spaces of P and the resistance curve is plotted.
- **Simplified Fall-of-Potential** — three measurements are made at defined distances of P and mathematical calculations are used to determine the resistance (to be described in more detail later).
- **61.8% Rule** — a single measurement is made with P at a distance 61.8% (62%) of the distance between the electrode under test and C.

The related test methods tend to be more complex and sophisticated requiring many measurements and/or a great deal of math. These methods have been developed to help overcome the problems faced when testing large ground systems or when there is limited space. A list of these methods follows:

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In addition, Megger has developed a version of Fall-of-Potential testing where the operator does not have to disconnect the ground rod under test from the electrical system. The ART (Attached Rod Technique) will be covered in Appendix III.

**Fall-of-Potential Method:** This three-terminal test is the method described previously with reference to Fig. 5. With a four-terminal tester, P₁ and C₁ terminals on the instrument are jumpered and connected to the earth electrode under test. With a three-terminal instrument, connect X to the earth electrode.

Although four terminals are necessary for resistivity measurements, the use of either three of four terminals is largely optional for testing the resistance of an installed electrode. The use of three terminals is more convenient because it requires one lead to be connected. The trade-off is that the resistance of this common lead is included in the measurement. Normally, this effect can be minimized by keeping the lead short, to accommodate simple test requirements. The small additional resistance thus introduced is negligible. When performing more complex tests or meeting stringent requirements, however, it may be better to use all four terminals by a lead from the P₁ terminal to the test electrode (connecting it inside the lead from C₁). This is a true four-wire test configuration which eliminates all lead resistance from the measurement.

![Typical use of a Megger digital ground resistance tester to perform fall-of-potential testing](image)
Effects of Different Reference Probe Locations

Now, you may ask: if the right location for probe $P$ is always 62 percent of the distance between the earth electrode and $C$, why bother with all the tests at other locations for $P$? Why not just drive $P$ in at the 62 percent distance and assume that the measured resistance is the correct earth resistance? The following should help answer these questions.

Minimum Distance for $C$: Consider Fig. 8 which shows earth shells around the earth electrode and reference probe $C$. In Fig. 8a, $C$ is so close to the earth electrode that the earth shells seriously overlap. Then you don’t get the leveling off of measured resistance as $P$ is moved away from the earth electrode; the shells of $C$ add to the shells of the earth electrode so the resistance keeps increasing.

Dead Earth Method: When using a four-terminal instrument, $P_1$ and $C_1$ terminals connect to the earth electrode under test; $P_2$ and $C_2$ terminals connect to an all-metallic water-pipe system. With a three-terminal instrument, connect $X$ to the earth electrode, $P$ and $C$ to the pipe system (Fig. 7). If the water system is extensive (covering a large area), its resistance should only be a fraction of an ohm. You can then take the instrument reading as being the resistance of the electrode under test.

The dead earth method is the simplest way to make an earth resistance test. With this method, resistance of two electrodes in series is measured — the driven rod and the water system. But there are three important limitations:

1. The waterpipe system must be extensive enough to have a negligible resistance.
2. The waterpipe system must be metallic throughout, without any insulating couplings or flanges.
3. The earth electrode under test must be far enough away from the water-pipe system to be outside its sphere of influence.

In some locations, your earth electrode may be so close to the water-pipe system that you cannot separate the two by the required distance for measurement by the two-terminal method. Under these circumstances, if conditions 1 and 2 above are met, you can connect to the water-pipe system and obtain a suitable earth electrode. As a precaution against any possible future changes in the resistance of the water-pipe system, however, you should also install an earth electrode.

Due to the many uncertainties associated with this method of testing, it should be considered using as a “last resort.”
In Fig. 8b, C is placed farther away. Then the measured resistance levels off enough and at the 62 percent distance it is very close to the actual earth resistance. The reason for having C farther away is to get assurance that the 62 percent value is “in line” with other values on the curve. The value could only be wrong (assuming there are no measuring mistakes) if the soil conditions at the 62 percent point vary from conditions at other points, causing changes in earth resistivity. Graded soil around construction sites or buried objects such as pipes can cause such localized deviations. Therefore, you want to get some degree of flatness or leveling off of your curve to make such a variation easily noticeable. At the same time, remember that the resistance will rise again in the electrical field of the current probe, so measurements in this area are to be avoided.

As a practical example of this effect, consider the case illustrated in Fig. 9. This shows two earth resistance curves for two locations of C. Curve A was obtained when C was 100 ft from the earth electrode; Curve B when C was 700 ft away. Curve A shows that C was too close to the earth electrode; Curve B shows the desired tendency toward leveling out of the measured resistance. The 62 percent distance gives resistance values nearly the same in this case since the earth resistivity is fairly uniform.

**Simplified Fall-of-Potential Test:** The preferred test method is to always gather sufficient data to plot the actual curve of resistance vs. distance. In the event that this is impossible, a simplified test might be used with a compromise on accuracy. This procedure is similar to that outlined under Fall-of-Potential Method as described in IEEE Standard No. 81 (see references), but you start with P midway between the earth electrode and C.

This reading with P at 50 percent of the distance from the earth electrode to C is noted as R1. Reference probe P is then moved to a location 40 percent of the distance to C. The reading at this point is noted as R2. A third reading, R3, is made with P at a 60 percent distance. The average of R1, R2 and R3 is calculated as RA. You determine the maximum deviation from the average by finding the greatest difference between individual readings and the average. If 1.2 times this percentage is less than your desired test accuracy, RA can be used as the test result. As an example of this technique, use the data from curve B in Fig. 9 as follows:

\[
R_1 = 58 \, \Omega \quad R_2 = 55 \, \Omega \quad R_3 = 59 \, \Omega
\]

\[
R_A = \frac{55 + 58 + 59}{3} = 57.3 \, \Omega
\]

\[
\frac{R_A - R_2}{R_A} = \frac{57.3 - 55}{57.3} = 4.0\%
\]

\[
4.0\% \times 1.2 = 4.8\%
\]

If your desired accuracy was 5 percent, 57 \, \Omega (R_A) could be used as the result. If the result is not within the required accuracy, probe C has to be placed farther away and the tests repeated. This method can give sufficient accuracy but will always give values on the low side. (See discussion following with reference to Table I.)

---

**Fig. 9: Example of how C location affects the earth resistance curve**
Some Rules of Thumb on Spacing P and C: For testing a single earth electrode, C can usually be placed 50 ft from the electrode under test, with P placed about 31 ft away. With a small grid of two earth electrodes, C can usually be placed about 100 to 125 ft from the electrode under test; P correspondingly can be placed about 62 to 78 ft away. If the earth electrode system is large, consisting of several rods or plates in parallel, for example, the distance for C must be increased to possibly 200 ft, and for P to some 125 ft. You’ll need even greater

Table I: Guide to approximate location of reference probes (see Note 1)

<table>
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<th>Distance to C, Ft.</th>
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<td>440</td>
</tr>
</tbody>
</table>

Note 1: Based upon data in Reference 2.
Note 2: For example, the diagonal across an area surrounded by an earthed fence.

Lazy Spikes

The latest designs of digital earth testers can operate with very high temporary spike resistances and still give reliable and accurate results. Because the current and voltage are measured separately, it enables electrode measurements to be carried out with test spike resistances up to 400 kΩ.

The advantage of these instruments tolerating such high spike resistance is generally that tests can be performed quickly on a green field site because electrodes do not have to be inserted too far into the ground. However, in urban situations, tests can be carried out using street furniture such as sign posts, metal fences and bollards. Where this is not possible, results have been obtained by laying the temporary electrodes on a wet patch of concrete. Coiled metal chains or metallized ground mats, with water poured over them, make an even better electrode because they conform more intimately to the earth’s surface than does a rigid spike. This technique has led to measured values of “spike” of less than 10 kΩ, well inside the maximum value that will cause an error to the reading.

With modern instruments, any problem with the temporary spikes will be indicated on the display to show that a reading may not be valid. A more suitable position for the spike may have to be used such as along the gap
between paving stones, a crack in concrete, or in a nearby puddle. As long as warning indicators do not appear, sufficient contact has been made and a reliable test may be performed.

**Supplementary Tests**

There are related tests which can be performed to supplement the information gained from the ground test and to augment the protection provided by the ground electrode. One of these is a continuity test to assure that it is complete and adequate throughout the grounding conductors and down to the point of contact with the electrode. Either a three-terminal or four-terminal tester can be used in a two-terminal configuration by shunting together the appropriate pairs. The two leads can thus be connected across a bond, weld, joint, or length of conductor, and the resistance measured. An earth tester, however, provides only a convenient backup check, not a fully rigorous continuity test. The reason for this is that, for safety’s sake, the test current is limited to values below a level harmful to the human body. A fully rigorous proof of a bond, however, must stress the connection at current levels capable of revealing corrosion, cracks, loose connections, and the like. For this reason, a dedicated low resistance ohmmeter capable of 10 A or more of test current is preferred.

To protect personnel about to perform a ground test, as well as to identify the presence of electrical problems in the system, the ground electrode can first be checked for the presence of fault current. It is not uncommon, in an unbalanced or faulted electrical system, for the electrode to be carrying a fault current, more or less constantly, to ground. This may be only a few milliamps or several amps, and occurring undetected. A sufficiently sensitive clamp-on milliammeter can reveal the problem, and protect the testing crew from possible shock, in just a few seconds.

The total impedance of the system can be measured at once by using a loop tester. This instrument simulates a fault between a phase conductor and ground, and thereby measures the total impedance of the entire ground loop, including conductors and the earth return path back to the transformer and its winding. If any of these elements have too high a resistance, protective devices may be inhibited from operating properly, even though the ground electrode itself is maintained at a sufficiently low resistance.

**How to Improve Earth Resistance**

When you find that your earth electrode resistance is not low enough, there are several ways you can improve it:

- Lengthen the earth electrode in the earth.
- Use multiple rods.
- Treat the soil.

**Effect of Rod Size:** As you might suspect, driving a longer rod deeper into the earth, materially decreases its resistance. In general, doubling the rod length reduces resistance by about 40 percent. The curve of Fig. 10 shows this effect. For example, note that a rod driven 2 ft down has a
Megger.

Resistance of 88 Ω; the same rod driven 4 ft down has a resistance of about 50 Ω. Using the 40 percent reduction rule, $88 \times 0.4 = 35$ Ω reduction. By this calculation, a 4-ft deep rod would have a resistance of 88 - 35 or 53 Ω — comparing closely with the curve values.

You might also think that increasing the electrode diameter would lower the resistance. It does, but only a little. For the same depth, doubling the rod's diameter reduces the resistance only about 10 percent. Fig. 11 shows this relationship. For example, a 10-ft deep rod, 5/8 in. in diameter, has a resistance of 6.33 Ω; increasing its diameter to 1-1/4 in. lowers the resistance to 5.6 Ω. For this reason, you normally only consider increasing the rod diameter if you have to drive it into hard terrain.

Use of Multiple Rods: Two well-spaced rods driven into the earth provide parallel paths. They are, in effect, two resistances in parallel. The rule for two resistances in parallel does not apply exactly; that is, the resultant resistance is not one-half the individual rod resistances (assuming they are of the same size and depth). Actually, the reduction for two equal resistance rods is about 40 percent. If three rods are used, the reduction is 60 percent; if four, 66 percent (see Fig. 12).
When you use multiple rods, they must be spaced apart further than the length of their immersion. There are theoretical reasons for this, but you need only refer to curves such as Fig. 13. For example, if you have two rods in parallel and 10-ft spacing, resistance is lowered about 40 percent. If the spacing is increased to 20 percent, reduction is about 50 percent.

**Treatment of the Soil:** Chemical treatment of soil is a good way to improve earth electrode resistance when you cannot drive deeper ground rods because of hard underlying rock, for example. It is beyond the scope of this manual to recommend the best treatment chemicals for all situations. You have to consider the possible corrosive effect on the electrode as well as EPA and local environmental regulations. Magnesium sulfate, copper sulfate, and ordinary rock salt are suitable non-corrosive materials. Magnesium sulfate is the least corrosive, but rock salt is cheaper and does the job if applied in a trench dug around the electrode (see Fig. 14). It should be noted that soluble sulfates attack concrete, and should be kept away from building foundations. Another popular approach is to backfill around the electrode with a specialized conductive concrete. A number of these products, like bentonite, are available on the market.

Chemical treatment is not a permanent way to improve your earth electrode resistance. The chemicals are gradually washed away by rainfall and natural drainage through the soil. Depending upon the porosity of the soil and the amount of rainfall, the period for replacement varies. It may be several years before another treatment is required.

Chemical treatment also has the advantage of reducing the seasonable variation on resistance that results from periodical wetting and drying out of the soil. (See curves of Fig. 15.) However, you should only consider this method when deep or multiple electrodes are not practical.

See Appendix 1 which describes the use of a nomograph relating length of rod, diameter of rod, and earth resistivity to earth resistance.

---

7, 8 Source: Reference 20
Dr. Frank Wenner of the U.S. Bureau of Standards (now NIST) developed the theory behind this test in 1915 (see reference 10). He showed that, if the electrode depth (B) is kept small compared to the distance between the electrodes (A), the following formula applies:

$$\rho = \frac{2 \pi A R}{B}$$

where \(\rho\) is the average soil resistivity to depth A in ohm-cm, \(\pi\) is the constant 3.1416, \(A\) is the distance between the electrodes in cm, and \(R\) is the Megger earth tester reading in ohms.

In other words, if the distance A between the electrodes is 4 ft, you obtain the average earth resistivity as follows:

1. Convert the 4 ft to centimeters to obtain A in the formula:
   $$4 \times 12 \times 2.54 \text{ cm} = 122 \text{ cm}$$

2. Multiply \(2 \pi A\) to obtain a constant for a given test setup:
   $$2 \times 3.14 \times 122 = 766$$

Now, for example, if your instrument reading is 60 \(\Omega\), the earth resistivity would be 60 x 766, or 45,960 ohm-cm.

---

B = 1/20A is generally recommended
Type of Soil Affects Resistivity

Whether a soil is largely clay or very sandy, for example, can change the earth resistivity a great deal. It isn’t easy to define exactly a given soil; “clay” can cover a wide variety of soils. Therefore, we cannot say that any given soil has a resistivity of so many ohm-cm. Tables II and III are taken from two different reference books and show the wide range in values. Note also the spread of values for the same general types of soil. See Fig. 18 also.

Table II: Resistivities of Different Soils*

<table>
<thead>
<tr>
<th>Soil</th>
<th>Resistivity (Ohm-cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fills: ashes, cinders, brine wastes</td>
<td>Avg: 2,370, Min: 590, Max: 7,000</td>
</tr>
<tr>
<td>Clay: shale, gumbo, loam</td>
<td>Avg: 4,060, Min: 340, Max: 16,300</td>
</tr>
<tr>
<td>Same: varying proportions of sand/gravel</td>
<td>Avg: 15,800, Min: 1,020, Max: 135,000</td>
</tr>
<tr>
<td>Gravel, sand, stones with little clay/loam</td>
<td>Avg: 94,000, Min: 59,000, Max: 458,000</td>
</tr>
</tbody>
</table>

*US Bureau of Standards Report 108

Practical Example of Test Method

A petroleum company had a 10-in. pipeline 6300 ft long running through rugged terrain. After a corrosion leak, they wanted to check out earth resistivity along the line. Low-resistance spots would most likely require attention. They used a Megger earth tester to make a survey along the line.

First, average depth of the pipeline was found from a profile map. It was 4 ft, so four electrodes were tied together 4 ft apart with strong cotton cord. They decided to check soil resistivity every 20 ft along the line. Fig. 17 shows a portion of the results; pit depth corrosion and Megger earth tester readings are plotted for points along the pipeline. Note that for low resistance readings, more corrosion was found.
**Resistivity Decreases with Moisture and Dissolved Salts**

In soil, conduction of current is largely electrolytic. Therefore, the amount of moisture and salt content of soil radically affects its resistivity. The amount of water in the soil varies, of course, with the weather, time of year, nature of sub-soil, and depth of the permanent water table. Table IV shows typical effects of water in soil; note that when dry, the two types of soil are good insulators (resistivities greater than $1000 \times 10^6$ ohm-cm). With a moisture content of 15 percent, however, note the dramatic decrease in resistivity (by a factor of 100,000). Actually, pure water has an infinitely high resistivity. Naturally occurring salts in the earth, dissolved in water, lower the resistivity. Only a small amount of salt can reduce earth resistivity quite a bit. (See Table V.) As noted in Section I, this effect can be useful to provide a good low-resistance electrode, in place of an expensive, elaborate electrode system.

**Table III: Resistivities of Different Soils**

<table>
<thead>
<tr>
<th>Soil</th>
<th>Resistivity (Ohm-cm) (Range)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Surface soils, loam, etc.</td>
<td>100 - 5,000</td>
</tr>
<tr>
<td>Clay</td>
<td>200 - 10,000</td>
</tr>
<tr>
<td>Sand and gravel</td>
<td>5,000 - 100,000</td>
</tr>
<tr>
<td>Surface limestone</td>
<td>10,000 - 1,000,000</td>
</tr>
<tr>
<td>Shales</td>
<td>500 - 10,000</td>
</tr>
<tr>
<td>Sandstone</td>
<td>2,000 - 200,000</td>
</tr>
<tr>
<td>Granites, basalts, etc.</td>
<td>100,000</td>
</tr>
<tr>
<td>Decomposed gneisses</td>
<td>5,000 - 50,000</td>
</tr>
<tr>
<td>Slates, etc.</td>
<td>1,000 - 10,000</td>
</tr>
</tbody>
</table>

*Evershed & Vignoles Bulletin 245

11 By “salt” we don’t mean the kind used to season food (sodium chloride), though this kind can occur in soil. Other kinds include copper sulfate, sodium carbonate, and others (see “Treatment of Soil,” Section I).

**Table IV: Effect of Moisture Content on Earth Resistivity**

<table>
<thead>
<tr>
<th>Moisture Content, Percent by Weight</th>
<th>Resistivity (Ohm-cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Top Soil</td>
<td>Sandy Loam</td>
</tr>
<tr>
<td>0.0</td>
<td>$1,000 \times 10^6$</td>
</tr>
<tr>
<td>2.5</td>
<td>250,000</td>
</tr>
<tr>
<td>5.0</td>
<td>165,000</td>
</tr>
<tr>
<td>10.0</td>
<td>53,000</td>
</tr>
<tr>
<td>15.0</td>
<td>21,000</td>
</tr>
<tr>
<td>20.0</td>
<td>12,000</td>
</tr>
<tr>
<td>30.0</td>
<td>10,000</td>
</tr>
</tbody>
</table>


**Table V: Effects of Salt Content on Earth Resistivity**

<table>
<thead>
<tr>
<th>Added Salt, Percent by Weight of Moisture</th>
<th>Resistivity, (Ohm-cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.0</td>
<td>10,700</td>
</tr>
<tr>
<td>0.1</td>
<td>1,800</td>
</tr>
<tr>
<td>1.0</td>
<td>460</td>
</tr>
<tr>
<td>5.0</td>
<td>190</td>
</tr>
<tr>
<td>10.0</td>
<td>130</td>
</tr>
<tr>
<td>20.0</td>
<td>100</td>
</tr>
</tbody>
</table>

*For sandy loam; moisture content, 15% by weight; temperature 63º F (17º C)
As covered in Section I, the other main reason for measuring earth resistivity is to design earth-electrode systems for electrical power systems, lightning arresters, and so on. The measured resistivity values are used in standard engineering formulas that calculate factors like number and depth of rods necessary to achieve a required ground resistance, thus reducing the amount of trial and error in the installation of an effective ground. Earth resistance varies directly with earth resistivity and it is helpful to know what factors affect resistivity.

The curves of Fig. 19 illustrate several worthwhile points. They show the expected change in earth resistance (due to resistivity changes) over a 1-1/2 year period; they also show that the deeper electrode reaches a deeper level to provide:

- Permanent moisture content (relatively speaking).
- Constant temperature (below frost line; again, relatively speaking).

**Seasonal Variations in Earth Resistivity**

We have seen the effects of temperature, moisture, and salt content upon earth resistivity. It makes sense, therefore, that the resistivity of soil will vary considerably at different times of year. This is particularly true in locations where there are more extremes of temperature, rainfall, dry spells, and other seasonal variations.

From the preceding discussion, you can see that earth resistivity is a very variable quantity. If you want to know what the value is at a given location, at a given time of year, the only safe way is to measure it. When you use this value for survey work, the change in the value, caused by changes in the nature of the sub-soil, is the important thing; from the variations in resistivity you can obtain useful survey results.

**Effect of Temperature on Earth Resistivity**

Not much information has been collected on the effects of temperature. Two facts lead to the logical conclusion that an increase in temperature will decrease resistivity: (1) water present in soil mostly determines the resistivity, and (2) an increase in temperature markedly decreases the resistivity of water. The results shown in Table VI confirm this. Note that when water in the soil freezes, the resistivity jumps appreciably; ice has a high resistivity. The resistivity continues to increase as temperatures go below freezing.

**Table VI: Effect of Temperature on Earth Resistivity***

<table>
<thead>
<tr>
<th>Temperature</th>
<th>Resistivity (Ohm-cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>20°F</td>
<td>7,200</td>
</tr>
<tr>
<td>10°C</td>
<td>9,900</td>
</tr>
<tr>
<td>0°C</td>
<td>13,800</td>
</tr>
<tr>
<td>0°C (ice)</td>
<td>30,000</td>
</tr>
<tr>
<td>-5°C</td>
<td>79,000</td>
</tr>
<tr>
<td>-15°C</td>
<td>330,000</td>
</tr>
</tbody>
</table>

*For sandy loam; 15.2% moisture

**Seasonal Variation of Earth Resistance with an Electrode of 3/4" Pipe in Stony Clay Soil**

Fig. 19: Seasonal variation of earth resistance with an electrode of 3/4" pipe in stony clay soil. Depth of electrode in earth is 3 ft for Curve 1 and 10 ft for Curve 2 (source: Ref. 9)
**Determining a Good Electrode Location**

A good, low-resistance earth electrode depends upon a low-resistivity soil in a spot where you can drive in your electrodes. There are two approaches to picking your location:

1. Drive rods in various locations to such depths as may be required and test their resistances while they are being driven.

2. Measure the earth resistivity before driving ground rods. Then calculate the number and length of rods required.

To get a low-resistance electrode in an unfavorable location, lay out straight lines 10 ft apart, covering the area. Drive four stakes 10 ft apart, but not more than 6 in. deep, along a line a-b-d-c, as shown in Fig. 20. Measure the resistance R between stakes b and c, using the method described for earth resistivity. Then, shift the stakes along the line in question to points b-c-d-e, c-d-e-f, and so on (see Fig. 20) and test until the entire line has been covered. Next, move to the next line and repeat the process until the whole chosen area has been covered. The location giving the lowest value for R has the lowest specific resistance for the soil to the chosen depth of 10 ft. The spot is likely to give you the best earth electrode.

If you want results affected by the average earth resistivity to a depth of 20 ft, repeat the survey on lines 20 ft apart and with stakes spaced 20 ft apart. Such surveys do not require much time and can pay off in ensuring a good grounding system.

**Alternate Method:** Another way is to drive rods or pipes in various locations to such depths as may prove practicable, testing their resistance while they are being driven. In this manner, you can usually tell at once when moisture or other good conducting earth is reached. However, the work involved is apt to be much more than with the first method.
After installation it is vital to check that the electrical grounding system meets the design criteria and should be measured periodically to ensure corrosion or changes in the soil’s resistivity do not have an adverse effect. Ground networks may not appear faulty until a fault occurs and a dangerous situation arises.

To obtain a sufficiently low value of ground resistance, ground systems may consist of an earth mat covering a large area or many interconnected rods. Suitable test techniques must be used for large systems to ensure that valid readings are obtained. This is unlike a small single ground rod (for example, a lightning protection system or residential ground) which can be simple to test.

**Testing Challenges in Large Ground Systems**

Securing valid measurements when testing large ground systems requires that proper techniques and instrumentation be used. The nature of substation and power station grounding systems and related conditions make testing far more complex than on a simple ground rod. Following are the three key challenges in testing substation ground systems:

1. The physically large area of a substation/power station ground system results in a large “resistance area” and, consequently, long distances to the test probes; ideally, the current test probe should be placed 10 times the maximum distance on the ground system (e.g., 3000 ft for a 300 ft\(^2\) ground grid) to find the “flat” portion of the characteristic resistance curve.

2. The large “resistance area” typically gives ground resistance values of less than 0.5 Ω; test instrument resolution is critical if small variances in readings are to be observed; if the test instrument does not have suitable resolution, instrument errors can overwhelm the results.
For the Slope Method to provide meaningful results, accurate measurement of the variations at different points is critical. Since large ground systems typically have resistance values of less than 0.5 Ω, the differences can be quite small. An instrument with 1 mΩ measurement resolution can indicate the small differences between low readings.

Noise is a major problem in testing large ground systems, and must be addressed to ensure accurate results. To be effective, the test instrument must be designed to overcome the effects of significant noise in the test environment. Among the technical capabilities that can help offset the noise problem are:

- A variable test frequency (rather than a single, fixed test frequency) which can help remove any stray noise that could affect the reading.
- A high peak-to-peak interference suppression level.
- A sophisticated filter system to reject more noise.
- Various current settings to improve the signal-to-noise ratio when necessary.

The other challenges faced in testing large ground systems relate to the capabilities of the test instrument. Improved technology has made it possible for instruments to be designed that address problems created by the characteristics and conditions found in and around large ground systems.
Another way to reduce the earth resistance would be to lower the earth resistivity. Note in Fig. 21 that if you draw a line from a reference point 1 (leaving rod depth and diameter unchanged), you would need to reduce earth resistivity to about 1000 ohm-cm to give the required 4-Ω earth resistance. You could do this by chemical treatment, as described earlier, but normally the deeper rod is the easier way.

To illustrate use of the nomograph, let’s take an example. Assume you have a 3⁄8 in. rod driven 10 ft into the soil. Your Megger instrument indicates an earth resistance of 6.6 Ω. But let’s say your specification for this resistance is “no more than 4 Ω.” To get this, you can change one or more of the three variables — the simplest and most effective being depth of the driven rod. To find the required depth to give you a 4 Ω earth resistance, proceed as follows: With a ruler, draw a line from the 10 ft point in the L line to the 3⁄8 in. point in the d line; this gives a reference point where the line crosses the q line. Connect this reference point with 6.6 Ω—the measured resistance on the R line, as shown in Fig. 21; read the value of earth resistivity when this line crosses the p line. The value is 2000 ohm-cm.

To determine the required rod depth for a 4 Ω earth resistance, draw a line from this point on the R line through the 2000 point on the p line until you cross the q line. The dashed line on Fig. 21 shows this step. Now, assuming you keep rod diameter unchanged, connect the 3⁄8 point on d line through your new reference point on q and extend the line to L. This gives you the required rod depth for the 4 Ω resistance value. Finally, take a new instrument reading to check the value, because earth resistivity may not be constant (as the nomograph assumes).

---

12 Reference 21
GETTING DOWN TO EARTH

APPENDIX II
Clamp-On Method

Fall-of-potential testing, and its modifications, is the only ground testing method that conforms to IEEE 81. It is extremely reliable, highly accurate and can be used to test any size ground system. Additionally, the operator has complete control of the test set-up and can check or proof his/her results by testing at different probe spacings. Unfortunately, the Fall of Potential method also comes with several drawbacks:

- It is extremely time consuming and labor intensive.
- Individual ground electrodes must be disconnected from the system to be measured.

The clamp-on ground testing method, although it does not conform to IEEE 81, does provide the operator with the ability to make effective measurements under the right conditions. The clamp-on methodology is based on Ohm’s Law (R=V/I). A known voltage is applied to a complete circuit and the resulting current flow is measured. The resistance of the circuit can then be calculated. The clamp-on ground tester applies the signal and measures the current without a direct electrical connection. The clamp includes a transmit coil that applies the voltage and a receive coil that measures the current.

For the clamp-on method to work, there must be a complete circuit already in place, as the operator has no probes and, therefore, cannot set up the desired test circuit. The operator must be certain that earth is included in the return loop. The tester measures the complete resistance of the path (loop) the signal is taking. All elements of the loop are measured in series. The method assumes that only the resistance of the test ground contributes significantly.

Figure 22 shows the basic methodology. The tester is clamped over RX. All test current travels through RX, but divides between the remaining resistances to return. Note that RX is assumed to be much, much greater than the remaining resistance. In a multiple ground system, the circuit can be considered a loop consisting of the individual ground electrode, a return path via all other electrodes and the mass of earth. The single electrode will have a higher resistance than the remainder of grounds connected in parallel.

Figure 22 shows a practical example of where the clamp-on method is highly effective. The application is an interconnected parallel ground, like a lighting string. The system neutral completes the return. The resistance of the loop could be calculated by:

\[
R_{\text{loop}} = R_6 + \frac{1}{\sum \frac{1}{R_i}}
\]

where, normally \( R_X \gg \frac{1}{\sum \frac{1}{R_i}} \)

For six similar electrodes with a resistance of 10 \( \Omega \), the loop resistance measured when testing each electrode would be:

\[
R_{\text{loop}} = 10\Omega + 2\Omega = 12\Omega
\]
There are several major advantages to the clamp-on method, but also a number of disadvantages. It is important for the operator to understand the limitations of the test method so that he/she does not misuse the instrument and get erroneous or misleading readings. A clamp-on tester is an important tool in the bag of a test technician, but cannot be the only instrument used.

The primary advantage of the clamp-on method is that it is quick and easy, as no probes have to be driven and the ground rod does not have to be disconnected from the system. The clamp-on method is only effective in situations with multiple grounds in parallel. It cannot be used on isolated grounds, as there is no return path, making it not applicable for installation checks or commissioning new sites. In addition, it cannot be used if an alternate lower resistance return exists not involving the soil, such as with cellular towers or substations.

The operator must also be aware of the subtleties of the test method to ensure accurate results and analysis. If another part of the ground system is in the “resistance area” of the electrode under test, the result will be lower than the true resistance of the electrode, which could lead to a false sense of security. The test is carried out at a high frequency to enable the transformers to be as small and practical as possible. The downside is that this approach is less representative of a fault at power frequency than the traditional ground testing frequency of 128 Hz.
A good return path is required for more accurate readings. A poor return path may give high readings. The connection must be on the correct part of the loop for the electrode under test, as a wrong connection can give a faulty reading. The operator must have a thorough understanding of the system to know exactly what is being measured. The method is susceptible to noise from nearby electrical apparatus and is less effective for very “low” grounds (extraneous elements in the reading become comparatively large).

A final disadvantage of the clamp-on ground tester is that there is no built-in proof for the method. With fall-of-potential testing, the operator can check the results by increasing the probe spacings. With the clamp-on method, the results must be accepted on “faith.”

As noted previously, a clamp-on ground tester should not be the only test instrument used. It is, however, an important part of the ground testing tool kit, along with a fall-of-potential tester. The clamp-on tester can be used to identify problems quickly. A fall-of-potential tester can then be used confirm those problem results. This approach allows the operator to save time but improves accuracy.

Figure 24 is an application where the clamp-on method is often misused. This example will help show why knowledge of the system is critical to making the correct test. The illustration shows the problems with trying to use a clamp-on ground tester on a cellular tower. Cellular towers are grounded at the base, with each guy wire grounded and all of them connected together in a ring of grounds. If the operator clamps around the head of one of the guy wire grounds, the test current will simply complete the circuit in the ground ring and not through the soil. Note that the test current circulates through the conductor that connects the individual elements (ground rods) that comprise the ring. As such, the clamp-on ground tester will not be measuring the quality of the ground system. The reading will actually be a reading of the resistance of the “loop.”

**Fig 24: Cellular tower — example of a misused application**
The first step is to measure the resistance ($R_T$) of the entire system using a typical fall-of-potential configuration. In this example, the reading for $R_T$ is 1.9 $\Omega$.

Step two involves measuring the total current ($I_T$) being injected into the system from C1. For this example, $I_T$ is 9.00 mA. The next step is to measure the amount of current ($I_U$) flowing to the service. In this case, $I_U$ is 5.00 mA. With these measurements, the voltage drop from the selected volume of soil to the point of the P2 can be determined as follows:

$$V = I_T \times R_T$$

$$V = 0.009 \text{ A} \times 1.9 \ \Omega$$

$$V = 0.017 \text{ V}$$

The current through the ground electrode ($I_G$) can also be determined.

$$I_G = I_T - I_U$$

$$I_G = 9.00 \text{ mA} - 5.00 \text{ mA}$$

$$I_G = 4.00 \text{ mA}$$

APPENDIX III
Attached Rod Technique (ART)

Fall-of-potential testing is extremely reliable, highly accurate, conforms to IEEE 81 and gives the operator complete control over the set-up. Unfortunately, it is exceedingly time consuming and labor intensive, and requires that the individual ground electrodes be disconnected from the system.

As described in Appendix II, the clamp-on testing is quick and easy, but has many limitations. It requires a good return path, is susceptible to noise, has reduced accuracies and cannot be used on isolated grounds. It is not applicable for installation checks or commissioning new sites and has no built in proof.

The Attached Rod Technique (ART) method of testing provides some of the advantages of clamp-on testing (not having to disconnect the ground electrode) while remaining true to the theory and methodology of fall-of-potential testing. To understand the method, it is necessary to understand the theory and math behind it. In theory, a fall-of-potential measurement could be made without disconnecting the ground electrode if additional measurements were made with an earth leakage clamp meter (milliamp meter). Figures 25 and 26 show the three measurements that would be made.
Using the voltage drop and the current through the ground electrode, the resistance of the ground electrode \( (R_G) \) can be determined.

\[
R_G = \frac{V}{I_G}
\]

\[
R_G = 0.017 \text{ V} \div 0.004 \text{ A}
\]

\[
R_G = 4.25 \text{ } \Omega
\]

As noted, this is a theoretical approach that requires perfect conditions. Any additional current flowing from the service through the ground electrode would reduce the accuracy of the measurement. The earth leakage clamp meter would have to filter out all but the current generated by the instrument through C1 to ensure accuracy. Additionally, this approach requires that a number of mathematical calculations be made.

The Attached Rod Technique is based on the theory outlined above. Figure 27 shows an ART test being made.

**Fig 27: Attached Rod Technique (ART) measurement**

Ground testers that are designed to make ART measurements include a special built-in current clamp that is placed between the C1 connection and the earth. This type of instrument includes noise protection and digitally filters out all currents other than that generated by the instrument. The instrument’s microprocessor automatically performs all the calculations necessary to generate a resistance measurement for the ground electrode.

The test is a fall-of-potential test, meaning that all the “rules” still apply. Ideally, the operator would take ten measurements and plot the results to determine true resistance. Proper probe spacing remains critical, and fall-of-potential procedure and methodology must be followed. As with a traditional fall-of-potential test, the results can be proofed by increasing the probe spacings.

The advantage of the ART method over traditional fall-of-potential testing is that the ground electrode under test does not have to be disconnected from the system.

**Using ART method with Megger DET3TC to test commercial ground without disconnecting the system**
The difficulties of measuring the resistance of large electrode systems involve the use of very long leads to connect the potential and current probes. An alternative method, in which such long leads are not necessary, has been devised. The basic principle is to obtain earth-resistance curves for several current-electrode spacings and, by assuming a number of successive positions for the electrical center of the system, to produce intersection curves which will give the earth resistance and the position of the electrical center.

Some rather difficult problems are encountered when the resistance of an earth-electrode system, consisting of a number of rods, tapes, etc., all connected in parallel and spread over a large area, is to be measured. The usual method of measurement that worked very well has one disadvantage; namely, that it is generally necessary to place the auxiliary current probe at a considerable distance from the earth-electrode system. In some cases, this distance can be as much as 3000 ft, and this is not always convenient or possible.

A method which does not require such long lengths of cable would obviously be better. Therefore, the following is suggested.

Suppose that all measurements are made from an arbitrary starting point O, the distance C to the current probe and the variable distance P to the potential probe being measured from this point. Then a curve such as abc (Fig. 28), giving the measured resistance against the value of P, can be obtained. Now suppose the electrical center of the earth-electrode system is actually at D, distance X from O. Then the true distance from the center to the current probe is C + X, and the true resistance is obtained when the potential probe is at a distance 0.618 (C + X) from D. This means that the value of P, measured from O, is 0.618 (C + X) - X. If X is now given a number of values, the corresponding values of P can be calculated and the resistance read off the curve. These resistances can be plotted against the values of X in another curve. When this process is repeated for a different value of C, and another curve of resistance against X obtained, the two curves should cross at the required resistance. The process can be repeated for a third value of C as a check. These curves are called intersection curves. It has been assumed that D, O and C are in the same straight line.

**Test at a Large Substation**

Tests were made at a station covering an area approximately 300 ft x 250 ft. The earthing system consists of a number of earth plates and rods joined together by copper cables. The testing line was run out from a point on the face approximately halfway along one side and the current electrode was placed at distances of 400, 600, 800, and 1000 ft from the starting point. The resulting earth-resistance curves are given in Fig. 29. The intersection curves are plotted and the final value of resistance is found in Fig. 30. It is reasonable to expect that this value is correct to within a few percent.
Megger

General Comments
It is the purpose of this method to reduce that distance to the current probe, and this appears to have been achieved, but there are some additional points to be noted. From the work which has been done on the method, there are certain limits to the distance to the current probe. To comply, if the earthing system is in the form of a square, the minimum distance to the current probe should not be less than the side of the square. On the other hand, the maximum distance should not be too great. If it is, the resulting curve is very flat, and the intersection point becomes rather indefinite. Again, for a square system, this maximum distance should not exceed twice the side of the square. For other shapes of earth-electrode systems, it is necessary to judge suitable minimum and maximum values for the distance to the current probe.

Fig. 29: Earth resistance curves for a substation

Fig. 30: Intersection curves for Fig. 29. The center of the triangle formed by the intersection, Fig 30 gives the earth resistance 0.146 Ω
APPENDIX V
Measurement of The Resistance of Large Earth Electrode Systems: Slope Method\textsuperscript{14}

It has been shown that the true earth resistance of an electrode system is obtained when the temporary potential $P$ is positioned at a distance from the electrical center of the system equal to 61.8 percent of the distance from the electrical center to the temporary current probe. This principle is used in the technique called “Intersecting Curves” explained in Appendix I. It becomes apparent that the method is complex in nature and requires some “trial and error” calculations.

A further technique was evolved and is described here. It is easier to use and has been shown to give satisfactory results, both in theoretical and practical cases, and when the soil is non-homogenous. It is called the Slope Method.

To apply this technique, perform the following step procedure.

1. Choose a convenience rod $E$ to which the Earth Tester can be connected. $E$ is one of many paralleled rods forming the complex earth system.

2. Insert the current probe at a distance ($D_C$) from $E$ (distance $D_C$ is normally 2 to 3 times the maximum dimension of the system).

3. Insert potential probes at distances equal to 20\% of $D_C$, 40\% of $D_C$ and 60\% $D_C$. See examples in step 4.

4. Measure the earth resistance using each potential probe in turn. Let these resistance values be $R_1$, $R_2$ and $R_3$ respectively.

\textbf{Examples:} 

$R_1 = 0.2 \times D_C$ \quad $R_2 = 0.4 \times D_C$ \quad $R_3 = 0.6 \times D_C$

5. Calculate the value of\[
\mu = \frac{R_3 - R_2}{R_2 - R_1}
\]

\textsuperscript{14}Reference 23

The resultant is called $\mu$ and represents the change of slope of the resistance/distance curve.

6. Refer to Table VII to find the corresponding value of $D_P/D_C$ for $\mu$.

7. Since $D_C$ (distance to the current probe) is already known, calculate a new $D_P$ (distance of the potential probe) as follows then insert the potential probe at this new distance from $E$.

\[D_P = D_P/D_C \times D_C\]

Now measure the earth resistance by placing the potential probe at this new distance $D_P$. This measurement is known as the “true” resistance.

8. Repeat the whole process for a larger value of $D_C$. If the “true” resistance decreases appreciably as $D_C$ is increased, it is necessary to increase the distance of $D_C$ still further. After making a number of tests and plotting the “true” resistance, the curve will begin to show less of a decrease and will indicate more stable readings. It is at this point the resistance of the grounding system is noted.

\textbf{NOTE:} As with other earth testing techniques, some experimentation may be necessary to ascertain if the practical result is as accurate as the theory appears to indicate.

The Slope Method has been designed to eliminate the need for impractically long leads by the ability to interpolate the correct distance along the combined resistance curve, i.e. the curve of the current probe’s resistance superimposed upon that of the tested grid, without sufficient spacing to produce the characteristic “flat portion” between.
One particular observation on the Slope Method is that if the calculation of $\mu$ is greater than that given in the table, the distance $C$ must be increased.

Secondly, before the measured values for $R_1$, $R_2$ and $R_3$ can be accepted with a degree of confidence, it is recommended that a curve be plotted which will identify any localized effects and eliminate uncharacteristic readings from the calculations. Thirdly, it is also suggested that the test be repeated in different directions and with different spacings. The various results should exhibit a reasonable degree of agreement.

### Table VII: Values of $\frac{D_p}{D_c}$ for Various Values of $\mu$

<table>
<thead>
<tr>
<th>$\mu$</th>
<th>$\frac{D_p}{D_c}$</th>
<th>$\mu$</th>
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</tr>
</thead>
<tbody>
<tr>
<td>0.40</td>
<td>0.643</td>
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<td>0.642</td>
<td>0.42</td>
<td>0.640</td>
<td>0.43</td>
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<td>0.57</td>
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<td>0.594</td>
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<td>0.76</td>
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The Four Potential Method is another method based on fall-of-potential that allows the user to overcome the problems posed by complex grounding systems where the electrical center of the ground system is difficult to locate. This method was first introduced by Dr. G.F. Tagg in a 1964 IEE paper. For the purpose of this booklet, we will cover the test method and the formulae by which the resistance of the ground system can be determined. The theory behind the method will not be covered, although it links the resistance values obtained by measurements at six different positions for the potential probe in four formulae with the true resistance ($R_\infty$), which would occur with an infinite distance to the current probe.

The test probes are set out as shown in Figure 32, with measurement made from the edge of the electrical system. The current probe is set a suitable distance away from the edge of the ground system. The potential probe is then placed at distances equal to 20%, 40%, 50%, 60%, 70% and 80% of the distance to the current probe and a test is made at each location. The resistance values obtained ($R_1$, $R_2$, $R_3$, $R_4$, $R_5$, and $R_6$) are then entered into four formulae.

The formulae used follow:

1) \[ R_\infty = -0.1187R_1 - 0.4667R_2 + 1.9816R_4 - 0.3961R_6 \]
2) \[ R_\infty = -2.6108R_2 + 4.0508R_3 - 0.1626R_4 - 0.2774R_6 \]
3) \[ R_\infty = -1.8871R_2 + 1.1148R_3 + 3.6837R_4 - 1.9114R_5 \]
4) \[ R_\infty = -6.5225R_3 + 13.6816R_4 - 6.8803R_5 + 0.7210R_6 \]

### Reference

15 Reference 24
**Megger.**

The four results for $R_\infty$ should substantially agree, and an average of the results can be calculated. However, because of the assumptions made in the theory of this method, it is possible that the result from equation (1) will be less accurate than the others. If the result from (1) is in variance from the other results, it can be ignored and the average calculated from the other three results.

One major drawback to this method is that it requires a large distance for dc. This distance can range up to 2,000 feet or more for ground systems covering a large area or of very low resistance.

---

**APPENDIX VII**

**Star Delta Method**

If the current probe is so close that it is within the field of the test ground, the mathematical proofs for the Slope Method and Intersecting Curves will prove unintelligible and indicate to the operator that a better test position must be found. If this condition prevails, and room is so limited that an acceptable spacing cannot be derived, it may be necessary to resort to the Star-Delta Method. Named for the configuration of the test probes and lines of measurement (a graphic of it resembles the familiar symbols for "delta" and "star" windings), this method saves space by employing a tight configuration of three probes around the test ground (Figure 33).

---

**Fig 32: Four potential method test configuration**

**Fig 33: Star-Delta test configuration**

---

16 Reference 25
Provided that the distances between “E” and the current probes is adequate (so the resistance areas do not overlap), the individual resistance of “E” can be determined as follows:

1] \[ R_1 = \frac{1}{3} [ (R_{12} + R_{13} + R_{14}) - (R_{23} + R_{34} + R_{42})/2 ] \]

2] \[ R_1 = \frac{1}{2} (R_{12} + R_{13} - R_{23}) \]

3] \[ R_1 = \frac{1}{2} (R_{12} + R_{14} - R_{42}) \]

4] \[ R_1 = \frac{1}{2} (R_{13} + R_{14} - R_{34}) \]

If the result from equation 1 matches substantially that from the other three equations, then satisfactory conditions have existed for the measurement. However, if one of the probes has been situated so that its resistance area has overlapped that of “E” or another of the probes, an obviously false reading (perhaps even a negative value of resistance) will be obtained. A false reading warns the operator to redo the test.

Performing calculations to obtain the values of R2, R3 and R4 would show which probe was at fault. The equations for R2, R3 and R4 follow:

R2 = \[ \frac{1}{2} (R_{12} + R_{23} - R_{13}) \]
R2 = \[ \frac{1}{2} (R_{12} + R_{42} - R_{14}) \]
R2 = \[ \frac{1}{2} (R_{23} + R_{42} - R_{34}) \]
R3 = \[ \frac{1}{2} (R_{13} + R_{23} - R_{12}) \]
R3 = \[ \frac{1}{2} (R_{13} + R_{34} - R_{14}) \]
R3 = \[ \frac{1}{2} (R_{23} + R_{34} - R_{42}) \]
R4 = \[ \frac{1}{2} (R_{14} + R_{42} - R_{12}) \]
R4 = \[ \frac{1}{2} (R_{14} + R_{34} - R_{13}) \]
R4 = \[ \frac{1}{2} (R_{42} + R_{34} - R_{23}) \]
Step potential is obtained in a similar way. This is the potential difference a person would experience between their feet if they walked over the ground in which a fault current existed.

Terminals “C1” and “C2” on the earth tester are connected as described for determining touch potential. Terminals “P1” and “P2” are connected to two potential spikes set up for test purposes. The spikes are hammered into the ground at positions “A” and “B” as shown in Fig. 35, about 3 ft apart (i.e., the approximate length of an average person’s step). (Note: “A” is nearest to “E” and is connected to terminal “P1.”)

The earth tester is operated in the normal way and a resistance measurement is made. This is the effective resistance between “A” and “B” as seen by the test current. Again, the maximum value of the current that would flow in the earth under fault conditions at the substation must be known.

The effective step potential can be calculated by multiplying the fault current by the earth resistance, again within a reasonable accuracy.

---

APPENDIX VIII
Determining Touch and Step Potential

Touch potential is the term given to the potential difference a person might experience across their body if they were, for example, standing on the ground outside the earthed perimeter fence of a substation and touching the fence at the time a fault to earth occurred.

To determine this value, an earth tester may first be used to find the earth resistance. It is connected as shown in Fig. 35.

Terminal “C1” of the earth tester is connected to the grounding system of the substation (e.g. at “E”) and terminal “C2” is connected to a current spike “C” (set up for testing purposes some distance away). Terminal “P1” is connected to the structure being tested (e.g. the perimeter fence which the person might touch) and terminal “P2” is connected to a potential spike “P” which is inserted into the ground about 3 ft away from the perimeter fence adjacent to the point of test on the fence (i.e. where the person might stand).

The earth tester is operated in the normal way and a resistance measurement made. This is the effective resistance between the point of test on the fence and the potential spike as seen by the test current. The maximum value of the current that would flow in the earth when a fault occurred at the substation must be known. The maximum fault current has to be calculated from parameters associated with the substation ratings involved; it is not necessarily straightforward.

The effective maximum touch potential can be calculated within a reasonable margin of accuracy (about 20 percent, depending how true the earth resistance measurement is), by multiplying the fault current by the earth resistance.
## APPENDIX IX

### Ground Testing Methods Chart

<table>
<thead>
<tr>
<th><em>Method</em></th>
<th>Best Applications</th>
<th>Advantages</th>
<th>Limitations</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Fall of Potential</td>
<td>Small electrode systems (1 or 2 rods/plates); complex systems if full resistance curve is plotted</td>
<td>Extremely reliable; conforms to IEEE 81; operator has complete control of test set-up</td>
<td>Requires long distances (and long test leads) to the test probes on medium and large systems; time consuming and labor intensive</td>
</tr>
<tr>
<td>2. Simplified Fall of Potential</td>
<td>Small and medium electrode systems</td>
<td>Easier to carry out than full Fall of Potential; much faster</td>
<td>Ineffective if the electrical center is unknown; less accurate than Fall of Potential as less measurements are being made</td>
</tr>
<tr>
<td>3. 61.8% Rule</td>
<td>Small and medium electrode systems</td>
<td>Simplest to carry out; minimal calculation; fewest number of test probe moves</td>
<td>Assumes perfect conditions; ineffective if electrical center is unknown; soil must be homogeneous; less accurate</td>
</tr>
<tr>
<td>4. Slope</td>
<td>Large ground systems like substations</td>
<td>Knowledge of electrical center not necessary; long distances to test probes not necessary</td>
<td>Susceptible to non-homogeneous soil; less accurate; requires math</td>
</tr>
<tr>
<td>5. Intersecting Curves</td>
<td>Large ground systems like substations</td>
<td>Knowledge of electrical center not necessary; long distances to test probes not necessary</td>
<td>Numerous calculations and drawing of curves</td>
</tr>
<tr>
<td>6. Dead Earth (Two Point)</td>
<td>Not recommended</td>
<td>Quick and simple to perform</td>
<td>Problems of possible resistance overlap; non-metallic (high resistance) return</td>
</tr>
<tr>
<td>7. Star Delta</td>
<td>Ground systems located in congested urban areas and/or rocky terrain where probe positioning is difficult</td>
<td>Long distances for test probe positioning not necessary</td>
<td>Resistance areas should not overlap; a number of calculations required</td>
</tr>
<tr>
<td>8. Four Potential</td>
<td>Medium to large ground systems</td>
<td>Knowledge of electrical center not necessary</td>
<td>Long distances to test probes is still required; a number of calculations required</td>
</tr>
<tr>
<td>9. Clamp-On</td>
<td>Simple ground system with existing return path through multiple grounds</td>
<td>Quick, easy; includes bonding and overall connection resistance</td>
<td>Effective only in situations with multiple grounds in parallel; susceptible to noise; no basis in standards; no built-in proof</td>
</tr>
</tbody>
</table>

*The Attached Rod Technique (ART) is based on Fall of Potential*
DET4TD
The DET4TD (part of Megger’s Contractor Series of earth/ground resistance testers) is a four-terminal digital model designed to measure ground resistance from 0.01 Ω to 2000 Ω and earth voltages up to 100 V. As a four-terminal unit, the DET4TD can also be used to make earth resistivity measurements. The unit is supplied complete with a carrying case, test leads and probes.

DET5/4R and DET5/4D
The DET5/4R and DET5/4D are four-terminal digital models designed to measure ground resistance from 0.01 Ω to 2000 Ω. As four-terminal units, they can also be used to make earth resistivity measurements. The DET5/4R comes with rechargeable batteries while the DET5/4D uses dry cells.

DET2/2
The incomparable DET2/2 is a four-terminal digital model designed to operate in the most difficult (and electrically noisy) of test environments and for use on large, critical ground systems. This model has an extra digit of resolution (to 0.001) on readings and includes an interference filter, test current control and, most important, adjustable test current frequency (105-160 Hz). As a four-terminal unit, the DET2/2 can also be used to make earth resistivity measurements.

250260
The model 250260 Direct Reading Ground Tester is the most successful tester ever introduced to the market. Its reputation for reliable measurement and field operation has made it required equipment in the Standard Operating Procedures of major organizations. The mechanical analog movement, ranging from 0.5 to 500 Ω, makes the tester a reliable tool under the worst of weather extremes.

GROUND TESTERS AVAILABLE FROM MEGGER®

DET10C and DET20C
The DET10C and DET20C measure earth/ground resistance and current flow by the clamp-on method. These models measure ground resistance from 0.025 Ω to 1550 Ω and ground leakage current from 0.2 mA to 35 A. Both models have extra large jaws (1.36 in/35 mm) and weigh only 1.65 lbs (750 g). The DET20C includes data storage and download capability.

DET3TD
The DET3TD (part of Megger’s Contractor Series of earth/ground resistance testers) is a three-terminal digital model designed to measure ground resistance from 0.01 Ω to 2000 Ω and earth voltages up to 100 V. The unit is supplied complete with a carrying case, test leads and probes.

DET3TA
The DET3TA (part of Megger’s Contractor Series of earth/ground resistance testers) is a three-terminal analog model designed to measure ground resistance from 0.01 Ω to 2000 Ω and earth voltages up to 100 V. The unit is supplied complete with a carrying case, test leads and probes.

DET3TC
The DET3TC (part of Megger’s Contractor Series of earth/ground resistance testers) is a three-terminal digital model that includes Attached Rod Technique (ART) capability. It is designed to measure ground resistance from 0.01 Ω to 2000 Ω and earth voltages up to 100 V. With the optional clamp, it will measure ground current from 0.5 mA to 19.9 A. The unit is supplied complete with a carrying case, test leads and probes.
References

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